













The Ensat[®] – self-tapping threaded insert ...

Ensat[®] is a self-tapping threaded insert with external and internal threads, cutting slots or cutting bores.

A continuous process of further development has brought about a number of major improvements to product characteristics. These inserts are protected by German and also foreign patents.

The Ensat[®] is screwed into a pre-formed or pre-drilled receiving hole and so automatically taps its own thread into the hole wall.

This ensures a backlashfree fit with extreme loading capacity.

Ensat®-3F 305

is a thread forming insert with 3 longitudinal grooves around its periphery

Fields of application

The Ensat[®] is used throughout the whole of the metal and plastics processing industry.

- Automotive
- Household appliance and office machinery production
- Electrical and laboratory supplies
- Plant and equipment construction
- Sports and lifestyle equipment
- Railed vehicles industry

Product features

- Universal application for all types of plastic, thermoset plastics, thermoset plastics, PU/PUR foam, Fibre-reinforced plastic (FRP), for hardwood and plywood, hard paper and metal.
- Maximum strength values in comparison to other systems. The diagram illustrates the withdrawing force in thermoplastic materials: In thermoset plastics and FRP, the values tend to be higher.
- Thin-walled Ensat[®] for restricted space conditions (residual wall thicknesses), and also suitable for screwing in using a thread tapping machine (same inside and outside pitch).

Slot version: WN 303, Three-hole version: WN 347/348 page 16 and 17.



Fig. 3

Ensat®-SBS 337/338

These cutting bores are shaped to serve as chip reservoirs. The chips created during the driving process stored here and cannot drop into sensitive equipment parts.

For additional sealing from below: Ensat[®] with closed floor Works standard 357/358. See publication no. 20, page 21.



The Ensat[®] in the workpiece ...

Installation recommendation

The Ensat[®] should be processed appr. 0,1 – 0,2 mm recessed (fig. 4). After processing, the Ensat[®] can be immediately subjected to load. If the component material permits subsidence of the Ensat[®] under load, the Ensat[®] can only execute an axial movement of 0,1 to 0,2 mm. In other words, the pretension of the screw union is largely retained, loosening of the screw connection under dynamic load is impeded.

Retaining hole

The receiving hole (L, fig. 5) can be simply drilled or already provided for in the casting.

Countersinking (N) the borehole (fig. 5) is recommended in order to:

- Prevent the workpiece surface from being raised
- Permit screwing in to a greater depth
- Ensure improved initial cutting characteristics



Guideline values for countersink: N = 0,06 to $0,08 \times E + E$

Material thickness: Smallest admissible material thickness \geq length of the Ensat[®]

Depth of the blind hole T: see Works Standard sheets, page 11 to 20 E = Outside diameter of the Ensat[®] [mm]



Fig. 4

Borehole diameter

Brittle, tough and hard materials call for a larger borehole than soft or elastic materials. For guideline values, see the table above.

Edge distance

The smallest still admissible edge distance W (fig. 5) depends on the planned stress level and the elasticity of the material into which the Ensat[®] is screwed. Guideline values for plastic: $W \ge 0.25$ to 0.9 E

For moulding parts made of additionell plastic, the Ensat[®] achieved, due to the greater effective shearing area, a higher pullout strength as a direct screw coupling in the same application.

Example:

Female thread M8, recommended borehole diameter for Ensat®-S 302: 10,9 to 11,2 mm Ensat®-SB 307/308: 11,1 to 11,3 mm (see Works Standard sheets)

In case of processing problems (e.g. extreme screw-in torque levels), it is generally of no consequence. In case of doubt, it is worth testing this.

Ensat[®]– driving tools...

On this page, you can configure the optimum tool for your application. A configuration is provided in the following as an illustrative example.

The article number is composed of two sequences of numbers and starts with the tool shank (fig. 8) which should be selected in accordance with your output.

Also encrypted in this number are the special versions for thin-walled Ensat[®] (620 1 and 621 1) and for very high driving torques (622 0 and 623 0) which are available as standard only as a square shank. Other non-standard geometries can be evaluated as standard besides the tools illustrated. The second sequence of numbers in the table (fig. 9) indicates the thread code of the female thread. The tightened dimensions of the tools are shown on the next page.

Tool for accessible retaining boreholes (short)



E1



B1

Fig. 6

The right length of the threaded pin for the Ensat[®] with cutting slot or with cutting bore is calculated from the pitch of the female thread (see also Fig. below; P = pitch of the female thread).



Setting or exchanging the stud

- Pull the shell (2) downwards off the shank (1).
- Release the locking screws (5).
- Screw the stud (7) in or out. Yellow colour marking indicates flattened surfaces for the locking screws.
- When assembling, tighten both screws (5) evenly.
- Insert the ball bearing (6).
- Push on the shell (2) until the ball stop locks into place.
 For the tool to function perfectly, the shell must be very easy to rotate.
 Shorten the thread of tool 610 accordingly for short Ensat[®].

 Unscrew the guide bush (3) at the front if the Ensat[®] is to be installed deeper than 0.2 mm under the surface of the workpiece. Diameter: 0.1 to 0.2 mm smaller than Ensat[®] retaining hole.

For mounting thin-walled Ensat[®] (page 17), special guide bushes must be used (tools 620 1 and 621 1).

Conditions for flawless tool function

- Locking and unlocking the tool on the Ensat[®] surface is guaranteed by a thrust bearing (6).
- The stop pins (4) execute the impact at the shell (2) which unlocks the tool.
- Wear at the stud (7) can result in unlocking problems.

The components are also offered as single parts to allow you to carry out your own repairs to the tool.

Simply give us a call.

Fig. 7

Ensat[®]– driving tools...



Example:

You wish to insert an Ensat® 308 000 050. 110. For the installation process, you have selected a driving tool with spindle hexagon socket to DIN ISO 1173 and have to mount the insert into a deep positioned borehole. Shank: 636 0... (long for deep positioned borehole)

Thread code: ...**00 050**... (for thread M5)

Suffix numbers: 000 (with always the same tools)

Order no: 636 000 050.000





For	M 2	M 2,5	M 3	M 3,5	M 4	M 5	9 W	M 8	M 10	M 12	M 14	M 16	M 18	M 20	M 22	M 24	M 27	M 30
Ensat®			No. 4	No. 6	No. 8	No. 10	1/4"	5/16"	3/8"	7/16"	1/2"	5/8"						
Metrisc	h00 020.000	00 025.000	00 030.000	00 035.000	00 040.000	00 050.000	00 060.000	00 080.000	00 100.000	00 120.000	00 140.000	00 160.000	00 180.000	00 200.000	00 220.000	00 240.000	00 270.000	00 300.000
cel-No. worth							00 525.000	00 531.000	00 537.000	00 544.000	00 550.000	00 562.000						
urtik UNC			00 604.000	00 606.000	00 608.000	00 610.000	00 625.000	00 631.000	00 637.000	00 644.000	00 650.000	00 662.000						
UNF			00 704.000	00 706.000	00 708.000	00 710.000	00 725.000	00 731.000	00 737.000	00 744.000	00 750.000	00 762.000						
			-					Measu	Irement	table			1					
Tool typ	oe 620 0 (sh	ort version), 620 1 (variant fo	r thin-wall	ed-ENSAT®) and 621 () (long ve	rsion), 621	1 (varian	It for thin-	walled-EN	SAT®)					
Ē	8	∞	∞	8	8	12,5	12,5	12,5	16	16	25	25	25	25	25	30	30	30
SW	6,3	6,3	6,3	6,3	6,3	10	10	10	12,5	12,5	20	20	20	20	20	25	25	25
8	78	78	78	78	78	95	95	95	118	118	145	145	145	169	169	198	198	198
B1	40	40	40	40	40	50	50	50	60	60	60	60	60	60	60	60	60	60
ш	18	18	18	18	18	24	24	24	32	32	50	50	50	58	58	70	70	70
E2	7	7	7	7	7	6	10	12	15	18	20	22	24	26	28	32	35	38
Tool typ	oe 622 0 (sh	ort version	1, reinforce	d version f	or high ins	tallation to	orques) an	1 623 0 (I	ong versio	1, reinforce	d version	for high in	stallation t	orques)				
ш	0	0	0	0	0	36	36	36	43	43	0	0	0	0	0	0	0	0
Tool typ	oe 630 0 (sh	ort version	ı, hexagona	al shaft) an	id 631 0	(long versid	on hexagoi	nal shaft)										
SW	11,11	11,11	11,11	11,11	11,11	11,11	11,11	11,11	11,11	11,11	11,11	11,11	11,11					
В	71	71	71	71	71	83	83	83	98	98	118	118	118					
Tool typ	oe 635 0 (sh	ort version	ו, hexagona	al shaft) an	id 636 0	(long versi	on, hexago	nal shaft)										
SW	6,35	6,35	6,35	6,35	6,35	6,35	6,35	6,35	6,35	6,35								
В	99	99	99	99	99	78	78	78	93	93								
Tool typ	oe 640 0 (sh	ort version	i, morse tap	per shaft)	and 641 0	. (long ver:	sion, morse	etaper sha	ft)									
MK	MKO	MKO	MKO	MKO	MKO	MK2	MK2	MK2	MK3	MK3	MK4	MK4	MK4	MK4	MK4	MK4	MK4	MK4
В	0	0	0	0	0	0	0	0	0	176,5	0	222,5	0	0	0	0	0	0
Tool typ	oe 626 0 (sh	ort version	ı, square so	ocket shan	k) and 627	0 (long v	rersion, squ	iare socket	shank)									
SW						1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"	1/2"
В						94,5	94,5	94,5	117,5	117,5	140,5	140,5	140,5	168,5	168,5	197,5	197,5	197,5
Tool typ	oe 610 2, 61	10 3 (fror	n M 8), 610) 4 (fron	1 M6) – (fo	r ENSAT® v	vith hexage	on socket)										
ш					9	∞	10	10	12	14	16	18						
в					80	06	100	100	110	125	125	125						
SW					4,9	6,2	∞	∞	6	11	12	15						
Tool typ	oe 610 0, 61	12 0 (man	ual driving	tools)														
ш		9	9	9	9	10	10	10	16	16	16							
В		55	55	60	60	75	75	75	95	95	95							
SW		5	5	5	5	8	8	8	12,5	12,5	12,5				—			
In order	to obtain the l	length dimen	sion of the e	xtended toc	I versions, th	ne specified u	dimensions l	3 must be ad	lded in each	case to the c	limension B	1.						

O = available on request

30.1218



Manual Ensat[®]installation ...



Fig. 10



Fig. 11

Manual Insertion Process

The manual insertion is usually carried out using the manual tool 610 0 ... via the female thread or in the case of the tools 610 2...using the hexagon socket. You can of course also use power tools for the manual assembly. If doing so, it needs to be ensured that the rotatable sleeve (2, see fig. 6) is in the corresponding correct position (see fig. 15 procedure description).

Image 10.1/11.1

Thread the Ensat[®], cutting geometry (slit or bore) has to be pointing downward. Attention needs to be paid while doing so that the screw with nut does not face in the direction of the cutting geometry after locking with a counter nut, as the shavings are otherwise not discharged.

Image 10.2/11.2

Screw in the Ensat[®] until approx. 0.1-0.2 mm underneath the surface of the work piece like in image 4 (during temporary assembly using screw and nut, the Ensat[®] should be processed until flat). Vertical assembly must be ensured.

Image 10.3/11.3

Loosen the counter nut, otherwise the ${\sf Ensat}^{\circledast}$ could possibly become unscrewed. Subsequently screw out the screw/screw-in tool.



Machine Ensat[®]installation...

Fig. 12

Machine driving process

- Precisely position the workpiece so that the bore and machine spindle are at right angles to each other (do not tilt).
 Set the machine to the precise installation depth (appr. 0.1 to 0.2 mm below the surface of the workpiece see page 5).
- 2. Actuate the operating lever of the machine. The rotatable outer shell of the tool must be resting against the outer visible stop pins at the beginning of the turning process so that it is driven by the pins in the clockwise direction.
- Feed the Ensat[®] towards the tool (slot or cutting hole facing downwards) and grip for the duration of 2 to 4 revolutions.
- 4. Continue to actuate the operating lever of the machine and to guide the tool to the hole until the Ensat[®] cuts into the borehole. The remainder of the driving process takes place without actuating the feed.
- 5. Switch on the reversing function (depending on the type and structure of the device, this takes place automatically by means of a limit switch / depth sensor). Avoid setting the tool down hard on the workpiece as this can lead to breakage of both the tool and the Ensat[®]. It can also damage the playfree fit of the Ensat[®] and so reduce the pull-out strength. If necessary, adapt the driving speed in line with the necessary reversal time.

Machine installation takes place using the driving tools illustrated on page 7, mounted in:

1. Thread tapping machine

2. Drill press

with reversing system by means of depth stop or thread cutting head. Without guide cartridge, without feed. Important: Do not exceed tightening torques.

3. Manual machine

With depth sensor and reversing system. See fig. 12.

4. Single or multiple installation machines

With pneumatic or electric drive; semi or fully automatic, computer controlled (CNC). Note different pitches.

Guideline speed values for light alloy:

Ensat [®] female thread	Speed rpm [min ⁻¹]
M 2,5/M 3	650 - 900
M 4 / M 5	400 - 600
M 6 / M 8	280 - 400
M 10 / M 12	200 - 300
M 14 / M 16	150 - 200
M 18 / M 20	120 — 200
M 22 / M 24	100 - 160
M 27 / M 30	80 - 140

Fig. 13

Torque M_D

The maximum admissible torque is dependent on:

- **1.** The axial load capacity of the tool stud
- 2. The pressure resistance capacity of the Ensat[®] in the axial direction

Guideline values for driving torques:

F .@		
Ensat®	IVI 2,5	1,5 NM
Ensat®	M 3	2,5 Nm
Ensat®	M 4	5,5 Nm
Ensat®	M 5	10 Nm
Ensat®	M 6	15 Nm
Ensat®	M 8	28 Nm
Ensat®	M 10	40 Nm
Ensat®	M 12	60 Nm
Ensat®	M 14	100 Nm
Ensat®	M 16	160 Nm
Ensat®	M 18	220 Nm
Ensat®	M 20	310 Nm
Ensat®	M 22	420 Nm
Ensat®	M 24	530 Nm
Ensat®	M 27	770 Nm
Ensat®	M 30	1050 Nm

Fig. 14



Fig. 15